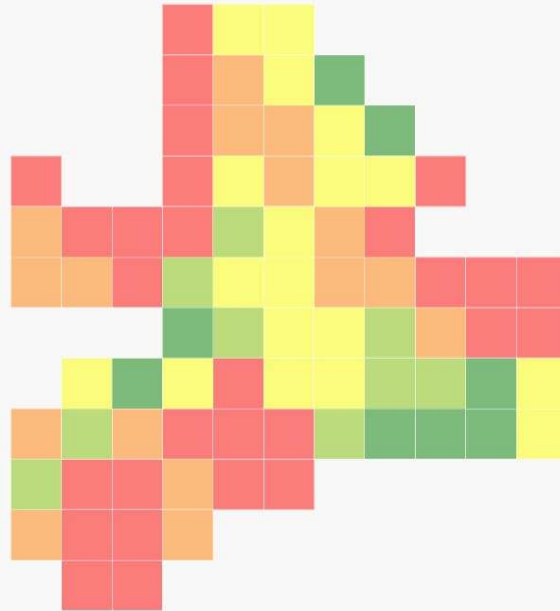


Completing the Map

with Street-level Imagery



#CompletheMap

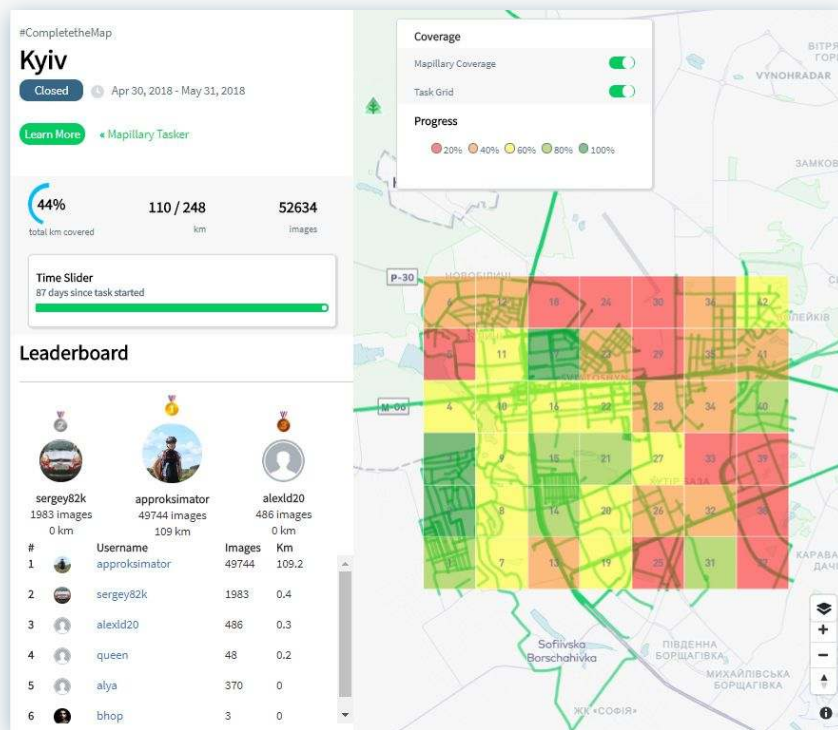


What is it?

- ▶ Web application for image capture tracking
- ▶ Grid-based tracking of task or challenge
- ▶ Leaderboard for community coordination, recognition, and competition
- ▶ Measurement of progress based on OSM road distances

Why?

- ▶ Targeted image collection
- ▶ Dashboard for community leaders

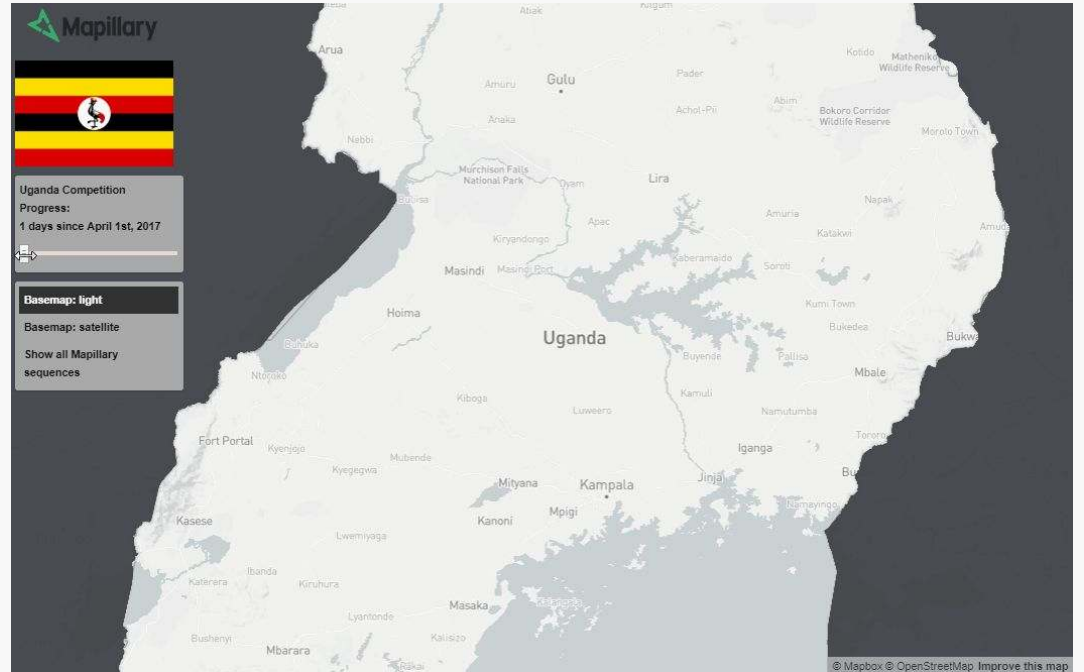


#CompletheMap



Phase I: Uganda

- ▶ April 2017
- ▶ Over 100k images from YouthMappers
- ▶ University chapters organised Mapillary photo walks
- ▶ Leaderboard showed user progress

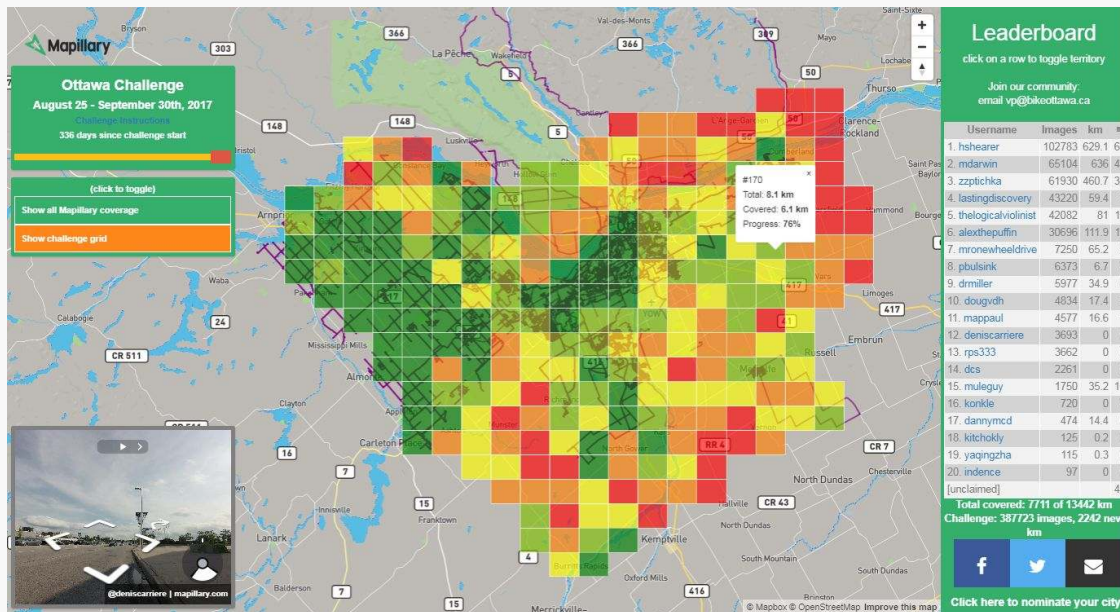


#CompleteTheMap



Phase II: Ottawa

- ▶ August 2017
- ▶ Over 450k images from Bike Ottawa
- ▶ Open source app, **zzptichka** heavily contributed (Yaro Shkvorets)
- ▶ First grid-based system, metro area
- ▶ Unified leaderboard and map
- ▶ Resulting data used for OSM and bike stress map





Challenges

- ▶ A better way to fetch and display contributor stats
- ▶ A better way to visualize progress
- ▶ A better way to see temporal change
- ▶ A better way to measure completion
- ▶ Reduce server load
- ▶ A DIY method to create a challenge

Solutions



- ▶ Leaderboard API (open)



- ▶ Simple grids, 5 quantiles



- ▶ Mapbox JS GL - filtering vector tiles by date, uniqueness



- ▶ Distance APIs -- unique and redundant (open)



- ▶ Run API calls hourly from preset GeoJSON shape



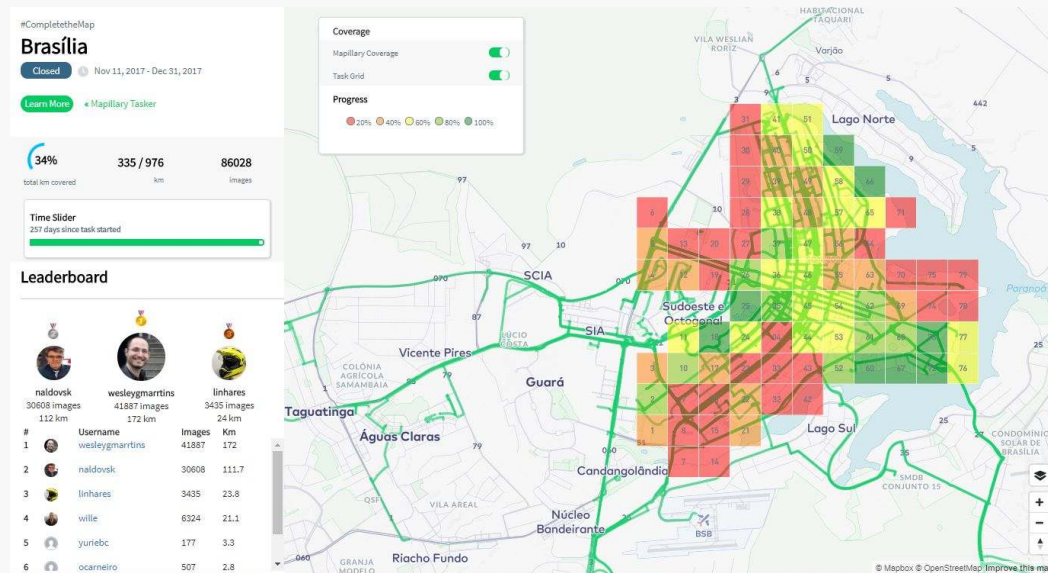
- ▶ Grid generator tool and modifiable settings script

#CompletheMap



Phase III: Brasilia

- ▶ November 2017
- ▶ Simplified layout
- ▶ More precise progress measurement
- ▶ Local users helped spread the word
- ▶ Over 86k images from OSM community
- ▶ 335km of OSM ways mapped



#CompleteTheMap

Mobile version

- ▶ Web address redirects on mobile
- ▶ Compact layout
- ▶ Location icon
- ▶ Useful for mapping on the go
- ▶ Best with an external camera



#CompleteTheMap

Lisboa

Active 🕒 Dec 31, 2017 - Dec 31, 2018

[How to Join](#) [Mapillary Tasker](#)

26% 270 / 1027 232175
total km covered km images

Time Slider

207 days since task started

Leaderboard



Do it yourself



Creating a grid

https://mapillary.github.io/mapillary_greenhouse/grid-generator/

- ▶ Draw rectangle, upload geojson, or choose center point
- ▶ Indicate network type, cell units
- ▶ Indicate cell size, and number of columns
- ▶ OSM Overpass API - road distances
- ▶ Variation of Geoff Boeing's **OSMNx**
- ▶ Geoprocessing with **Turf.js**

Grid Generator

Specify dates:
Start: End: Cell units: kilometers | Network Type: drive

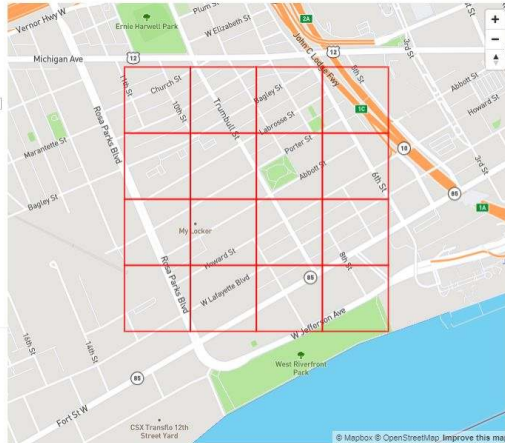
Option 1: Load a GeoJSON file, and create a custom grid (not limited to rectangular)
 No file chosen

Option 2: Hold Shift + Drag on map to draw bounding box.

Option 3: Enter a centerpoint for your grid, along with a total area width. This will generate a square grid.
Longitude: Latitude: Width:

Output 1: Cell Size indicates approximate height and width of grid squares. Your grid will contain the bounding box you draw, and may be larger to fit square cells.
Cell Size:

Output 2: Cell dimensions generates the number of columns you want, and square grids will be generated to match (distance auto-generated).
Columns:



Do it yourself

Creating a task

- ▶ Choose a city size area or smaller
- ▶ Add **grid.geojson** to directory
- ▶ Choose start and end date
- ▶ Edit **settings.js** to add details
- ▶ Submit to Mapillary for server-side hourly processing



```
//Chronological Information
var mindate = 1515024000000;
var maxdate = 1517443200000;
var mindateISO = new Date(mindate).toISOString();
var maxdateISO = new Date(maxdate).toISOString();

//Geographic Information
var city = 'Lisboa';
//enter country, state, territory, province, or other region name
var country = 'Portugal';
//name of the challenge folder, usually just the city unless the city has been done before
var challenge = 'lisboa';
```

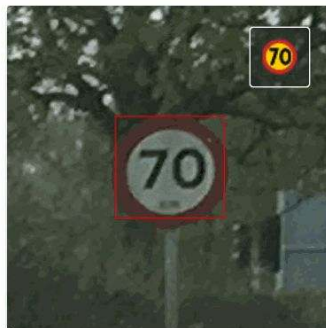


Verify the results



Teaching the computer

- ▶ Users can help improve algorithms
- ▶ Validating detections as accurate
- ▶ Traffic signs that are validated can be precisely positioned with computer vision
- ▶ Thousands of verifications ensure world class data quality
- ▶ Traffic signs detected in > 1 photo are added to traffic sign tiles in OSM iD



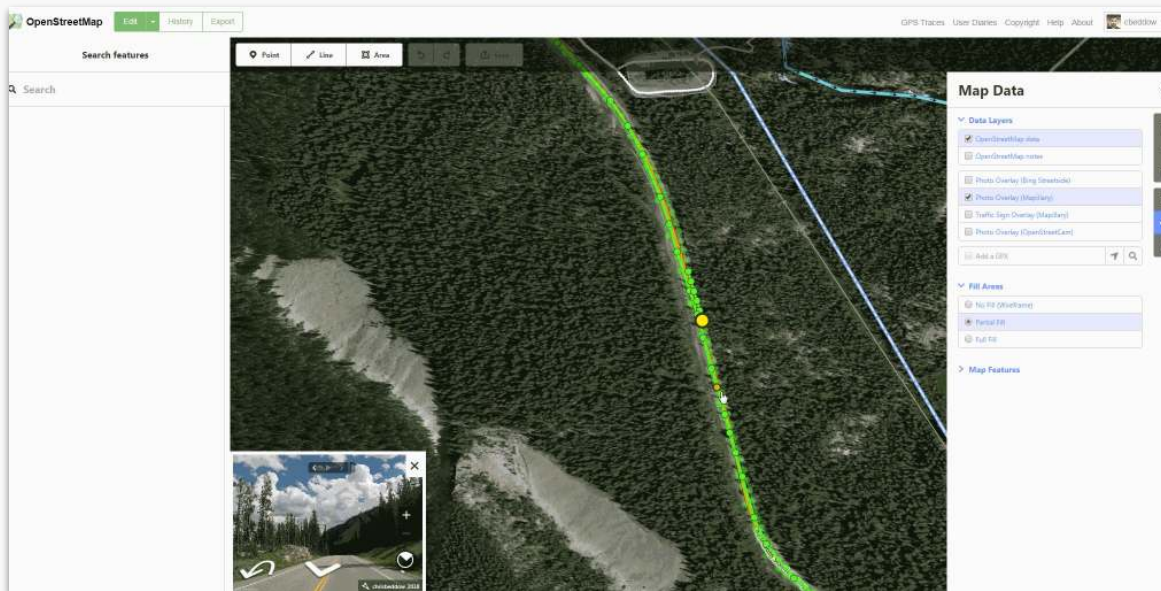
LEADERBOARDS		
RANK	USERNAME	POINTS
1	 @impaled	11160
2	 @yod4z	9795
3	 @chris_debian	4000
4	 @descilla	3883
5	 @dk72	3650
6	 @serj_nickel	3625
7	 @canadarunner	3538
8	 @gladi	3297
9	 @brinkenber	3107
10	 @neogeografen	2706
11	 @gitne	2609
12	 @piooip	2214
13	 @seba020	1788

Back to the map



Using images in OSM

- new** ▶ **OSM ID:** resize viewer
- new** ▶ **JOSM:** 360 degree image support
- ▶ Traffic sign overlay - precise positions due to computer vision
- ▶ 326 million photos worldwide
- ▶ More new features on the way

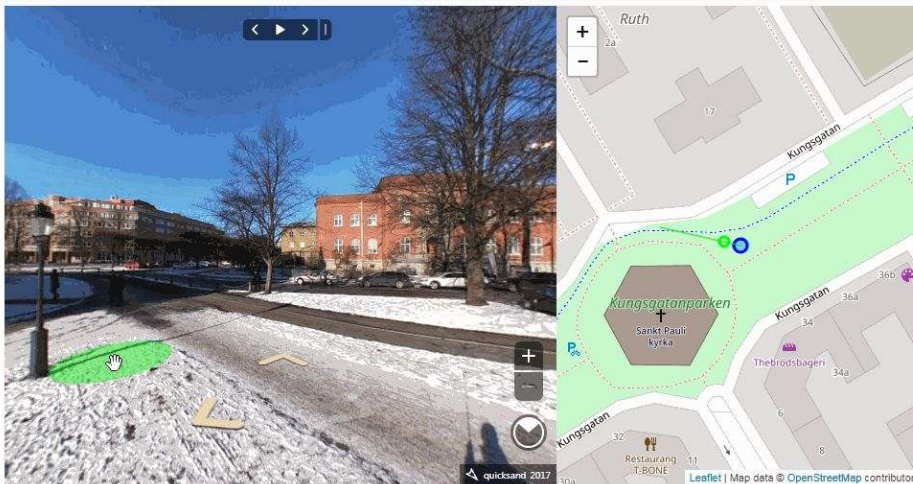


Enhanced Editing

Placement Tools

<http://mapillary.github.io/mapillary-js/>

- ▶ Click in image to add map points
- ▶ Planned for OSM ID
- ▶ Available now in open-source library: **Mapillary-JS**



[Open ↗](#)

index.html

```
<!DOCTYPE html>
<html>
<head>
  <meta charset='utf-8' />
  <title></title>
  <meta name='viewport' content='initial-scale=1,maximum-scale=1,user-scalable=no' />
  <link rel='stylesheet' href='https://unpkg.com/mapillary-js@2.12.1/dist/mapillary.min.css' />
  <link href='https://unpkg.com/leaflet@1.0.1/dist/leaflet.css' rel='stylesheet' />

  <script src='https://unpkg.com/mapillary-js@2.12.1/dist/mapillary.min.js'></script>
  <script src='https://unpkg.com/leaflet@1.0.1/dist/leaflet.js'></script>

  <style>
    html, body { margin:0; padding:0; height: 100%; }
    #mly { position: absolute; width: 60%; height: 100%; }
    #map { position: absolute; width: 40%; height: 100%; right: 0; }
  </style>
</head>
```

Highlights



2018 Global Challenge

- ▶ 1 - 31 May, 2018
- ▶ Ballerup, Denmark - 65k images/100km
- ▶ Kyiv, Ukraine - 52k images/109km
- ▶ Washington, DC, USA - 72k images/70km
- ▶ Funchal, Madeira - 63k images/81km
- ▶ Heredia, Costa Rica - 15k images/79km
- ▶ San Donato Milanese, Italy - 30k images/40km
- ▶ Myanmar, Hungary, Spain, Scotland, Canada, Lithuania, and more

#	Username	Location	Country	UKM	Images	Score [?]
1	neogeografen	Ballerup	Denmark	88	56234	304.45
2	approsimador	Kyiv	Ukraine	103	48014	242.9
3	danbjoseph	Washington D.C.	United States	72	71937	231.86
4	nunocaldeira	Funchal	Portugal	79	61587	211.17
5	elotrojames	Heredia	Costa Rica	49	5481	120.48
6	marcuscalabresus	San Donato Milanese	Italy	39	30661	91.43
7	mghla	Mandalay	Myanmar	43	12277	73.05
8	cristinadc	Sevilla	Spain	55	9592	71.89
9	elopio	Heredia	Costa Rica	20	2725	51.01
10	arcvancouver	Richmond	Canada	40	4791	49.69
11	991.2gt3	Markham	Canada	24	2653	29.98
12	kati	Ballerup	Denmark	9	4339	28.4
13	ccbb7766	Edinburgh	Scotland	18	2297	26.59
14	aleksasfi	Vilnius	Lithuania	12	4522	24.28
15	plumgarden	Ann Arbor	United States	13	2360	19.24
16	lamar839	York	England	7	7400	16.65
17	naylinnaung	Mandalay	Myanmar	11	1134	16.36
18	thelogicalviolinist	Carlington, Ottawa	Canada	0	8945	13.85
19	chicc0	Eching	Germany	5	4579	12.66
20	fmonge	Heredia	Costa Rica	5	535	12.64
21	daalso	Astoria	United States	7	3107	12.33
22	esiezar	Heredia	Costa Rica	2	1660	8.69
23	fod	Ballerup	Denmark	2	1057	7.46
24	snaysard	Reutlingen	Germany	3	2220	7.09
25	kmendezcr	Heredia	Costa Rica	0	2642	6.6
26	isapeixoto	Funchal	Portugal	1	1382	4.88
27	dzsombor96	Nyíregyháza	Hungary	1	2216	4.35
28	chris2	Edinburgh	Scotland	0	2655	4.03
29	sergey82k	Kyiv	Ukraine	0	1983	3.84
30	mun6u14cr	Heredia	Costa Rica	0	646	3.36

Map your world



Next Global Challenge

- ▶ 1 - 31 August, 2018
- ▶ Tweet to [@mapillary](https://twitter.com/mapillary) using hashtag [#Completemap](https://twitter.com/hashtag/Completemap) to nominate your city
- ▶ Current participants include **Norway, Sweden, Brunei, Costa Rica, Colombia, Uzbekistan, Australia, Denmark, Russia, Germany, Belarus, Falkland Islands/Malvinas, Spain, USA**
- ▶ Top 3 mappers receive a GoPro Hero 5 Black
- ▶ No setup required, we'll make a dashboard





Building better maps

- ▶ Better measurement of OSM edits from images
- ▶ Better OSM editing tools for street-level imagery
- ▶ Better data extraction using computer vision and structure from motion
- ▶ Better access to machine learning data layers



